

Confidence sequences for sequential experimentation

Steve Howard

Joint work with Aaditya Ramdas, Jon McAuliffe, and Jasjeet Sekhon

August 5, 2022

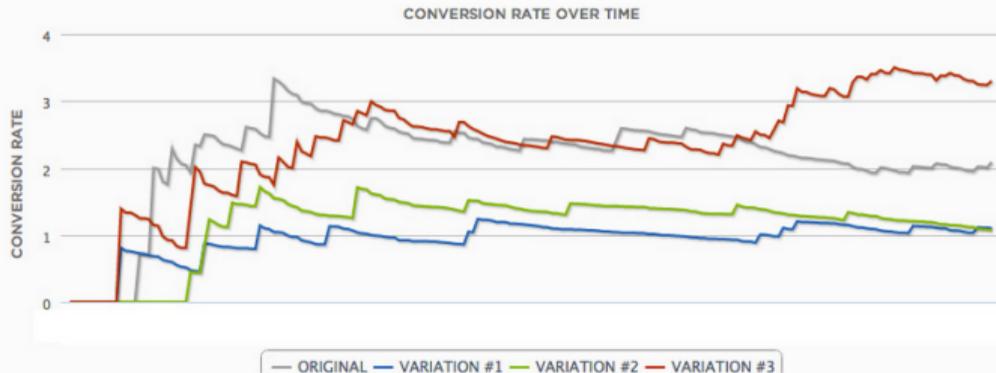
Sequential monitoring of experiment results is problematic.

Click on the button

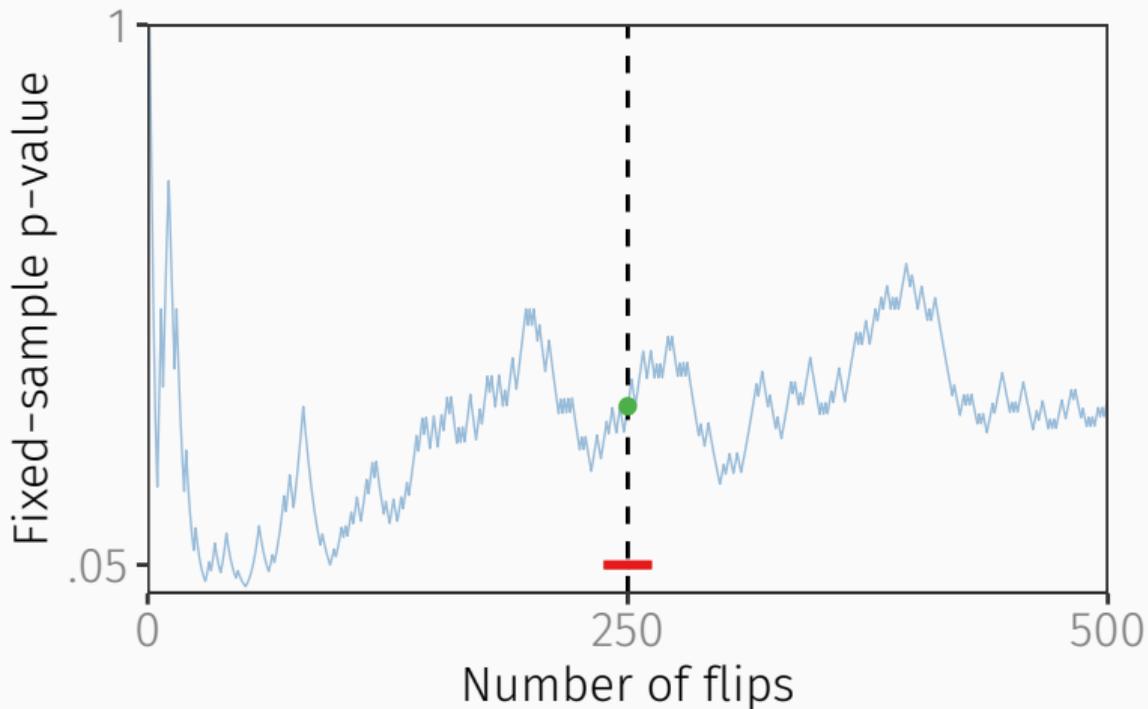
The percentage of visitors who clicked on a tracked element.

✔ Variation #3 is beating Original by +58.0%.

VARIATIONS	VISITORS	CONVERSIONS	CONVERSION RATE	IMPROVEMENT	CHANCE TO BEAT BASELINE ?
Variation #3	970	32	3.3% ($\pm 1.12\%$)	+58.0%	95.2%
Original <small>BASELINE</small>	1,006	21	2.1% ($\pm 0.88\%$)	---	---
Variation #1	999	11	1.1% ($\pm 0.65\%$)	-47.3%	3.9%
Variation #2	1,027	11	1.1% ($\pm 0.63\%$)	-48.7%	3.3%

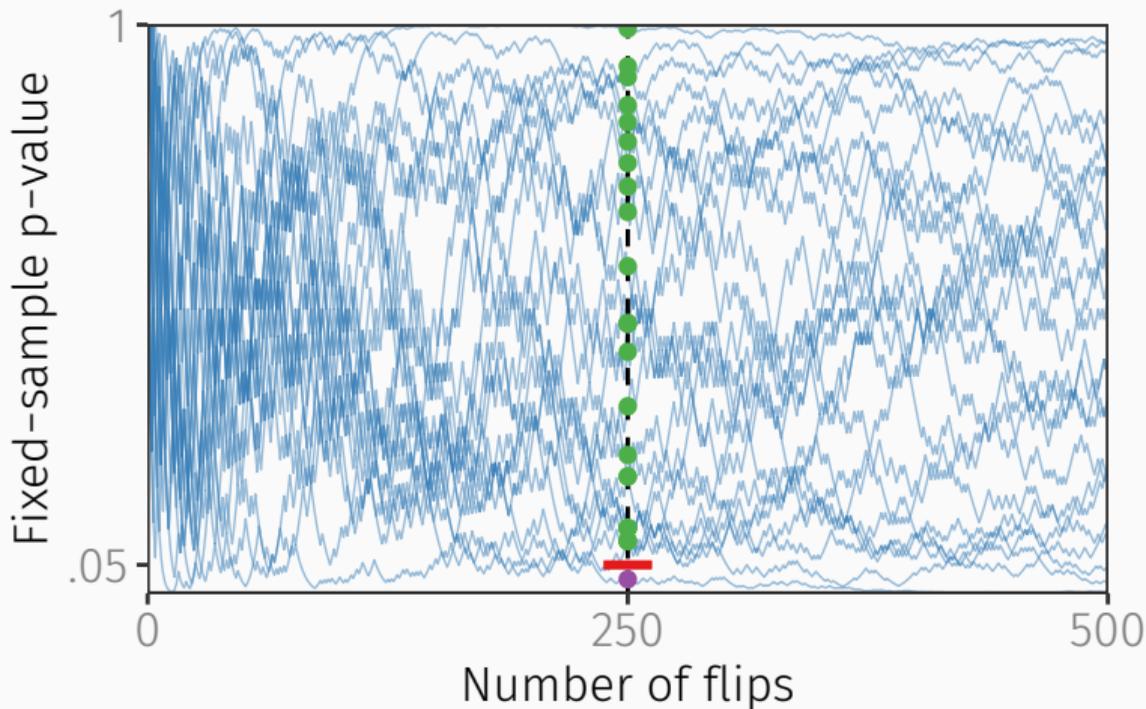


One path of p -values from a fair coin



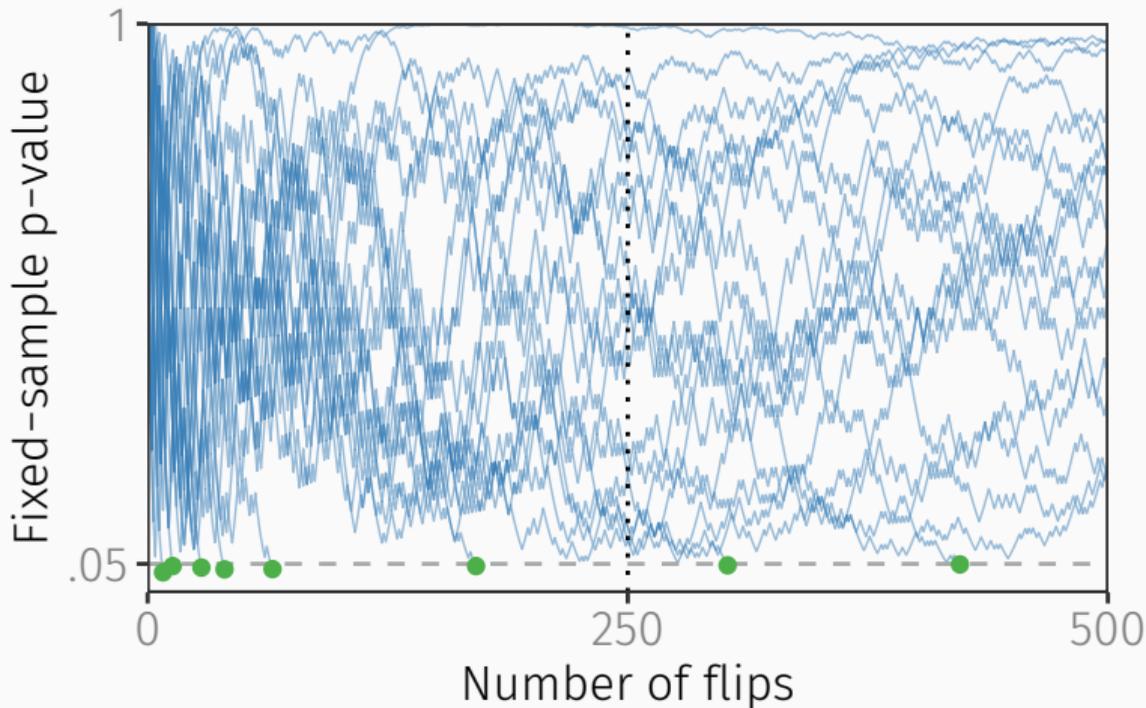
Let's look at many such paths...

With no bias, we only rarely conclude the coin is biased.



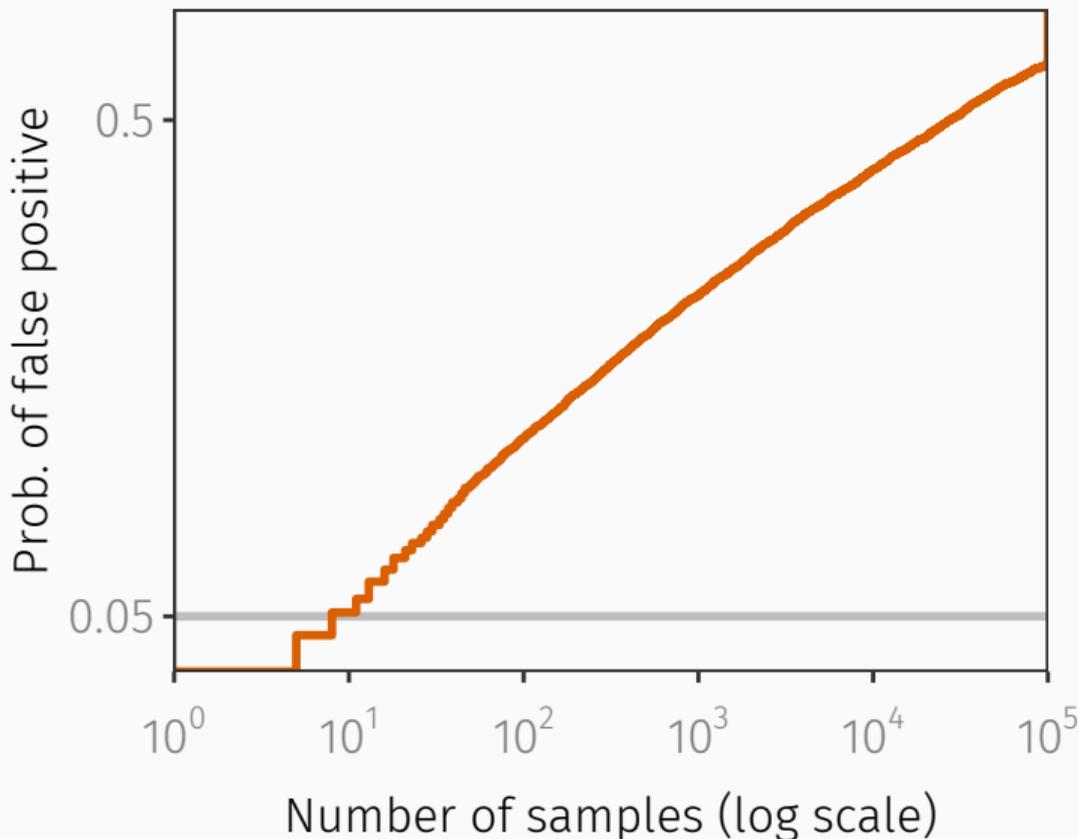
Just one out of 25 p -values is below 0.05.

Continuous monitoring of fixed-sample p -values inflates the false positive rate.



Here, with a fair coin, eight out of 25 paths reach significance.

The false positive rate grows arbitrarily large with enough flips.



Confidence sequences solve the problem of continuous monitoring.

A **confidence sequence** for $(\theta_t)_{t=1}^{\infty}$ is a sequence of intervals $(\text{CI}_t)_{t=1}^{\infty}$ satisfying

$$\mathbb{P}(\theta_t \in \text{CI}_t \text{ for all } t \in \mathbb{N}) \geq 1 - \alpha.$$

[Darling and Robbins 1967, Lai 1984, Jennison and Turnbull 1989, Johari et al. 2015, H. et al. 2021]

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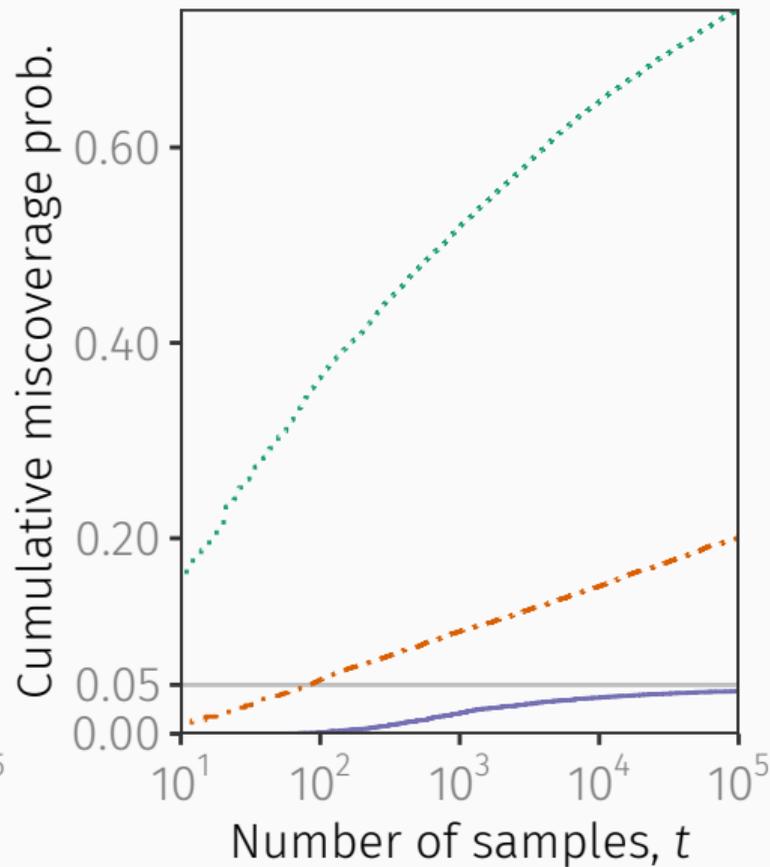
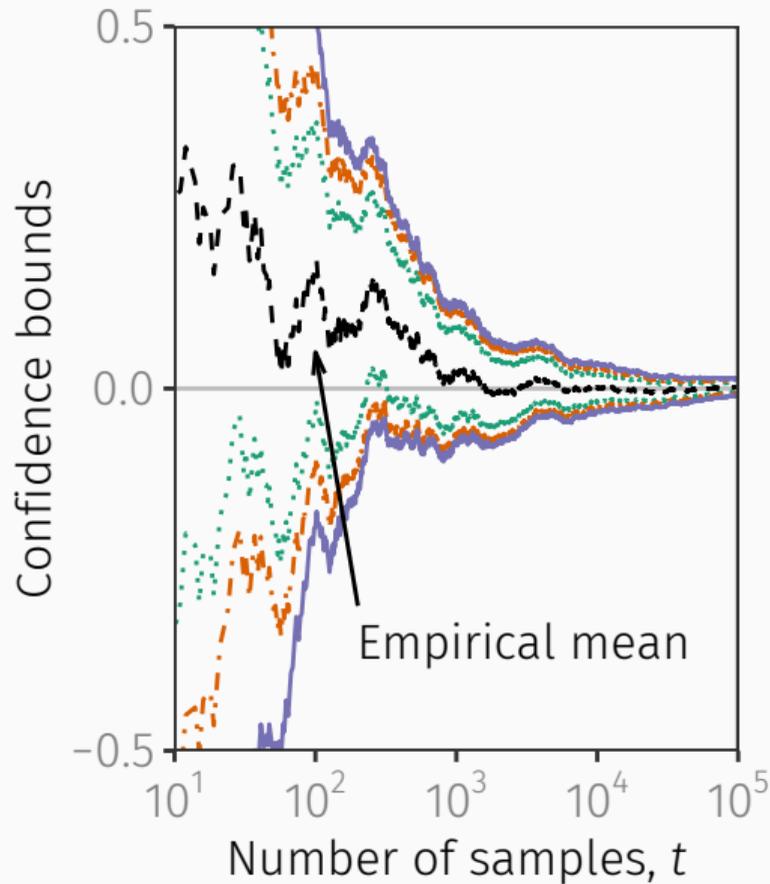
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Much stronger than the fixed-sample guarantee:

$$\text{For all } t \in \mathbb{N}, \mathbb{P}(\theta_t \in CI_t) \geq 1 - \alpha.$$

In short, we achieve this by making confidence intervals wider.



..... CLT
 - - - - Hoeffding
 ———— Confidence sequence

Outline

Some key results

Frequently asked questions

Confidence sequence for regression coefficients

Some key results

Empirical-Bernstein confidence sequence for bounded random variables

Theorem (H., Ramdas, McAuliffe, Sekhon 2021)

Suppose X_i are independent and $[a, b]$ -valued for all i . Let \hat{X}_i be any predictable sequence and u_α be any sub-exponential uniform boundary with scale $b - a$.

Then

$$\mathbb{P} \left(|\bar{X}_t - \mathbb{E}\bar{X}_t| < \frac{u_\alpha \left(\sum_{i=1}^t (X_i - \hat{X}_i)^2 \right)}{t} \text{ for all } t \in \mathbb{N} \right) \geq 1 - 2\alpha.$$

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Here $u_\alpha(v)$ is $\mathcal{O}(\sqrt{v \log v})$ or $\mathcal{O}(\sqrt{v \log \log v})$.

What about that boundedness assumption?

Without some similar assumption, it is impossible to construct a confidence interval.

The problem: one outlier can have arbitrarily large influence, e.g.

$$X_i = \begin{cases} 0, & \text{with probability } 1 - \epsilon, \\ 1/\epsilon, & \text{with probability } \epsilon. \end{cases} \quad (1)$$

Expectation is always one, but you need $\sim 1/\epsilon$ observations to have any idea about this.

Asymptotic arguments often sweep this issue under the rug. (In practice, though, they're usually satisfactory.)

Choosing a uniform boundary in practice

Some advice for choosing the uniform boundary function $u_\alpha(\cdot)$:

- Two-sided normal mixture is a nice starting point.
 - Simple closed form: eq. (14) of <https://arxiv.org/pdf/1810.08240.pdf>
 - Asymptotic justification: Waudby-Smith et al. (2021) “Time-uniform central limit theory with applications to anytime-valid causal inference”
- For choosing the tuning parameter ρ :
 - Sec. 3.5 of <https://arxiv.org/pdf/1810.08240.pdf>
 - Sec. 5 of <https://arxiv.org/pdf/1906.09712.pdf>
- For non-asymptotic guarantees, need to go deeper
- State-of-the-art for bounded random variables: Waudby-Smith & Ramdas (2022) “Estimating means of bounded random variables by betting”

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Unit i has fixed potential outcomes $Y_i(0), Y_i(1)$, for $i = 1, 2, \dots$

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$$\text{ATE}_t := \frac{1}{t} \sum_{i=1}^t [Y_i(1) - Y_i(0)].$$

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Assumption: $Y_i(k) \in [0, 1]$ for $k = 0, 1$, all i .

Average treatment effect: theorem

For each unit i , X_i is unbiased for the individual treatment effect $Y_i(1) - Y_i(0)$,

$$X_i := \hat{Y}_i(1) - \hat{Y}_i(0) + \left(\frac{Z_i - p}{p(1-p)} \right) \left(Y_i^{\text{obs}} - \hat{Y}_i(Z_i) \right)$$

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Theorem (H., Ramdas, McAuliffe, Sekhon 2021)

Assume no interference and $Y_t(k) \in [0, 1]$ for all k, t . Let u_α be any sub-exponential uniform boundary with scale $2 / \min\{p, 1 - p\}$. Then

$$\mathbb{P} \left(|\bar{X}_t - \text{ATE}_t| < \frac{u_\alpha \left(\sum_{i=1}^t (X_i - \hat{X}_t)^2 \right)}{t} \text{ for all } t \in \mathbb{N} \right) \geq 1 - \alpha.$$

The point: we can reduce ATE estimation to bounded mean estimation.

General treatment of adaptive allocation

What if assignment probability is time-changing (but predictable) P_t ? Just replace p with P_t :

$$X_t := \hat{Y}_t(1) - \hat{Y}_t(0) + \left(\frac{Z_t - P_t}{P_t(1 - P_t)} \right) \left(Y_t^{\text{obs}} - \hat{Y}_t(Z_t) \right).$$

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If we assume a stationary mean, can just use ordinary confidence sequence and ignore assignment probabilities.

Quantile estimation

X_1, X_2, \dots i.i.d. from any distribution F . Let q be the p^{th} quantile of F , let $\hat{Q}_t(p)$ denote the p^{th} sample quantile at time t .

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Theorem

Suppose X_i are i.i.d. from any distribution F . Let $u_{\alpha,p}$ be an appropriately scaled sub-Bernoulli uniform boundary. Then

$$\mathbb{P} \left(\hat{Q}_t \left(p - \frac{u_{\alpha,1-p}(t)}{t} \right) \leq q \leq \hat{Q}_t \left(p + \frac{u_{\alpha,p}(t)}{t} \right) \text{ for all } t \in \mathbb{N} \right) \geq 1 - \alpha.$$

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No assumption on the distribution F .

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Using package `confseq`

```
u(t) = confseq.boundaries.beta_binomial_mixture_bound(  
  p * (1 - p) * t, alpha,  
  g = 1 - p, h = p,  
  v_opt = ...)
```

Estimation of a cumulative distribution function

Theorem

Suppose X_i are i.i.d. from any distribution F . Let \hat{F}_t denote the empirical cumulative distribution function at time t . Then

$$\mathbb{P} \left(\left\| \hat{F}_t - F \right\|_{\infty} \leq A \sqrt{\frac{\log \log(et) + C}{t}} \text{ for all } t \in \mathbb{N} \right) \geq 1 - e^{-\mathcal{O}(A^2 C)}.$$

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Using package `confseq`

```
u(t) = confseq.quantiles.empirical_process_lil_bound(  
  t, alpha, t_min=1)
```

Frequently asked questions

What about the intersection CI?

If $\mathbb{P}(\theta \in \text{CI}_t \text{ for all } t \in \mathbb{N}) \geq 1 - \alpha$, then it also holds that

$$\mathbb{P} \left(\theta \in \bigcap_{s \leq t} \text{CI}_s \text{ for all } t \in \mathbb{N} \right) \geq 1 - \alpha, \quad (2)$$

Pro: smaller CIs

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Cons:

- Not valid for time-varying estimands (θ_t)
- Can become empty
- Not a function of sufficient statistics at time t

See sec. 6 of <https://arxiv.org/pdf/1810.08240.pdf>.

What about group sequential methods?

Key distinguishing features of group sequential methods:

- Require interim analysis schedule specifying a small number of “peeks”, planned in advance
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Cons:

- Require more planning and expertise
- Only valid asymptotically
- Typically involve a finite endpoint
- Not appropriate for continuous monitoring

What about Bayesian methods?

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- Some confidence sequence methods have a Bayesian interpretation.
- Bayesian methods are a good way to introduce shrinkage, which can help with selection bias. (But they come with no guarantees about bias, which is a frequentist concept.)

Dawid (1994) “Selection paradoxes of Bayesian inference” is a nice reference.

Confidence sequences for regression coefficients

Basic mechanism for mean estimation

- Suppose X_1, X_2, \dots are i.i.d. and we wish to estimate $\mathbb{E}X_1$.
- $S_t(\theta) := \sum_{i=1}^t (X_i - \theta)$ is a martingale when $\theta = \mathbb{E}X_1$.
- Uniform martingale concentration $\Rightarrow |S_t(\theta)| \leq u_t$ for all t with high probability.
 - We need some extra information about $X_i - \theta$, for example boundedness.
- Invert to get confidence sequence: $CI_t := \{\theta : |S_t(\theta)| \leq u_t\}$.

Martingales from univariate score functions

We just need a function $g(x, \theta)$ such that $\mathbb{E}g(X_i, \theta) = 0$ at the desired value of θ .

- $g(X_i, \theta) = X_i - \theta$ estimates the mean $\mathbb{E}X_i$
- $g(X_i, \theta) = 1_{X_i \leq \theta} - p$ estimates the p -quantile
- In general, $g(X_i, \theta) = f'(X_i, \theta)$ estimates the population minimizer of the smooth, convex loss f .
 - Confidence sequence for any M-estimator.

Vector-valued martingales from multivariate score functions

There are uniform concentration results for vector-valued martingales, e.g.,

$$\|S_t(\theta)\|_2 \leq u_t \text{ for all } t \text{ with high probability,} \quad (3)$$

where $S_t(\theta)$ takes values in R^d .

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Let

$$f(y_i, X_i, \theta) = \frac{1}{2} \|y_i - X_i^T \theta\|_2^2 \quad (4)$$

$$g(y_i, X_i, \theta) = \nabla f(y_i, X_i, \theta) = X_i^T (y_i - X_i^T \theta). \quad (5)$$

Then $S_t(\theta) = \sum_{i=1}^t g(y_i, X_i, \theta)$ is a martingale when θ is the population OLS coefficients.

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(Straightforward in principle; implementation may be challenging.)

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Summary

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- We derive useful confidence sequences in a variety of nonparametric settings, including for estimating average treatment effects under adaptive allocation, quantiles, and CDFs.

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- Peeking is a serious problem, and confidence sequences are a flexible solution which allow continuous monitoring.
- We derive useful confidence sequences in a variety of nonparametric settings, including for estimating average treatment effects under adaptive allocation, quantiles, and CDFs.
- Estimating vector-valued minimizers of general loss functions is a frontier.
 - For examples of vector-valued confidence sequences, see Abbasi-Yadkori et al. (2011) “Improved Algorithms for Linear Stochastic Bandits”, or Corollary 10 of <https://arxiv.org/pdf/1808.03204.pdf>.

Thank you!

- `steve@stev Howard.org`
- Time-uniform Chernoff bounds via nonnegative supermartingales (2020):
`https://arxiv.org/abs/1808.03204`
- Time-uniform, nonparametric, nonasymptotic confidence sequences (2021):
`https://arxiv.org/abs/1810.08240`
- Sequential estimation of quantiles with applications to A/B-testing and best-arm identification (2022): `https://arxiv.org/abs/1906.09712`
- Some state-of-the-art papers on the websites of Aaditya Ramdas and Ian Waudby-Smith.
- Implementations of many uniform boundaries and confidence sequences:
`https://github.com/gostev Howard/confseq`
- Slides: `stev Howard.org`

Appendix

We construct an unbiased estimator of each individual treatment effect.

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Two key properties of X_t :

1. **Unbiased:** $\mathbb{E}X_t = Y_t(1) - Y_t(0)$
2. **Variance** of X_t depends on **prediction errors** $(Y_t(1) - \widehat{Y}_t(1))^2$ and $(Y_t(0) - \widehat{Y}_t(0))^2$.

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Let $S_t = \sum_{i=1}^t X_i$. Then S_t/t is unbiased for ATE_t .

CLT confidence bounds

$$\frac{S_t}{t} \pm \frac{1.96 \sqrt{\sum_{i=1}^t (X_i - \bar{X}_t)^2}}{t}$$

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Uniform, non-asymptotic confidence bounds

$$\frac{S_t}{t} \pm \frac{u_\alpha \left(\sum_{i=1}^t (X_i - \hat{X}_i)^2 \right)}{t} \quad \text{where } \hat{X}_i = \hat{Y}_i(1) - \hat{Y}_i(0).$$

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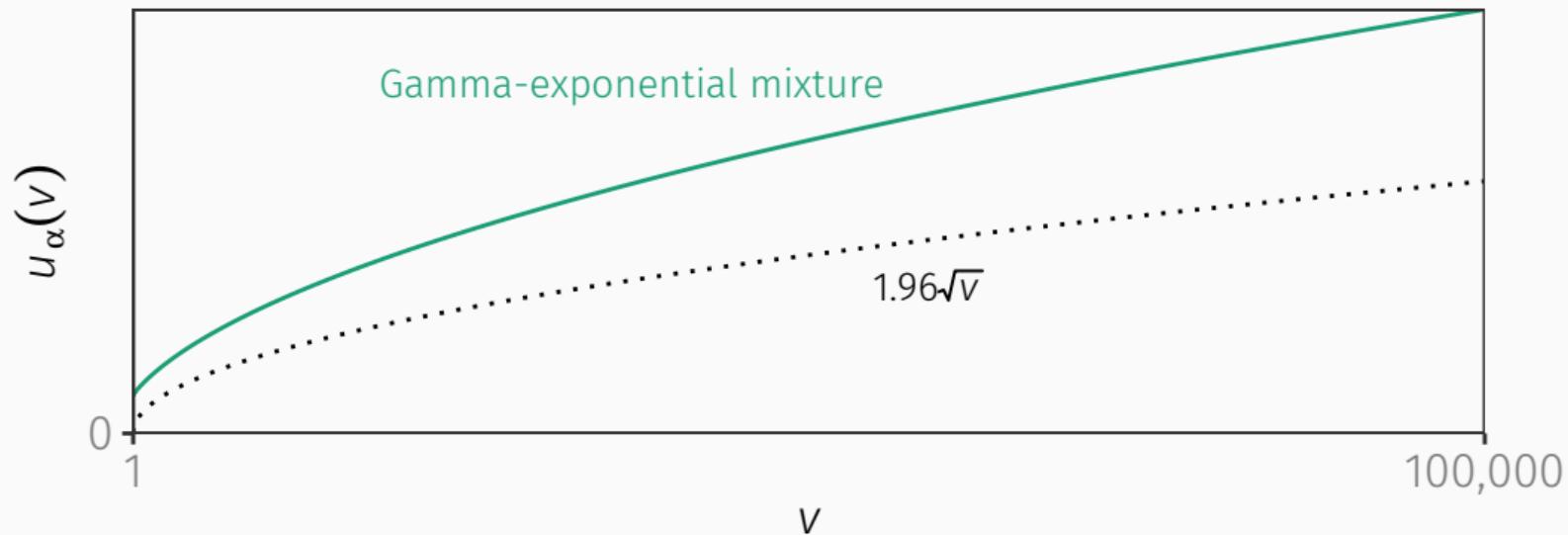
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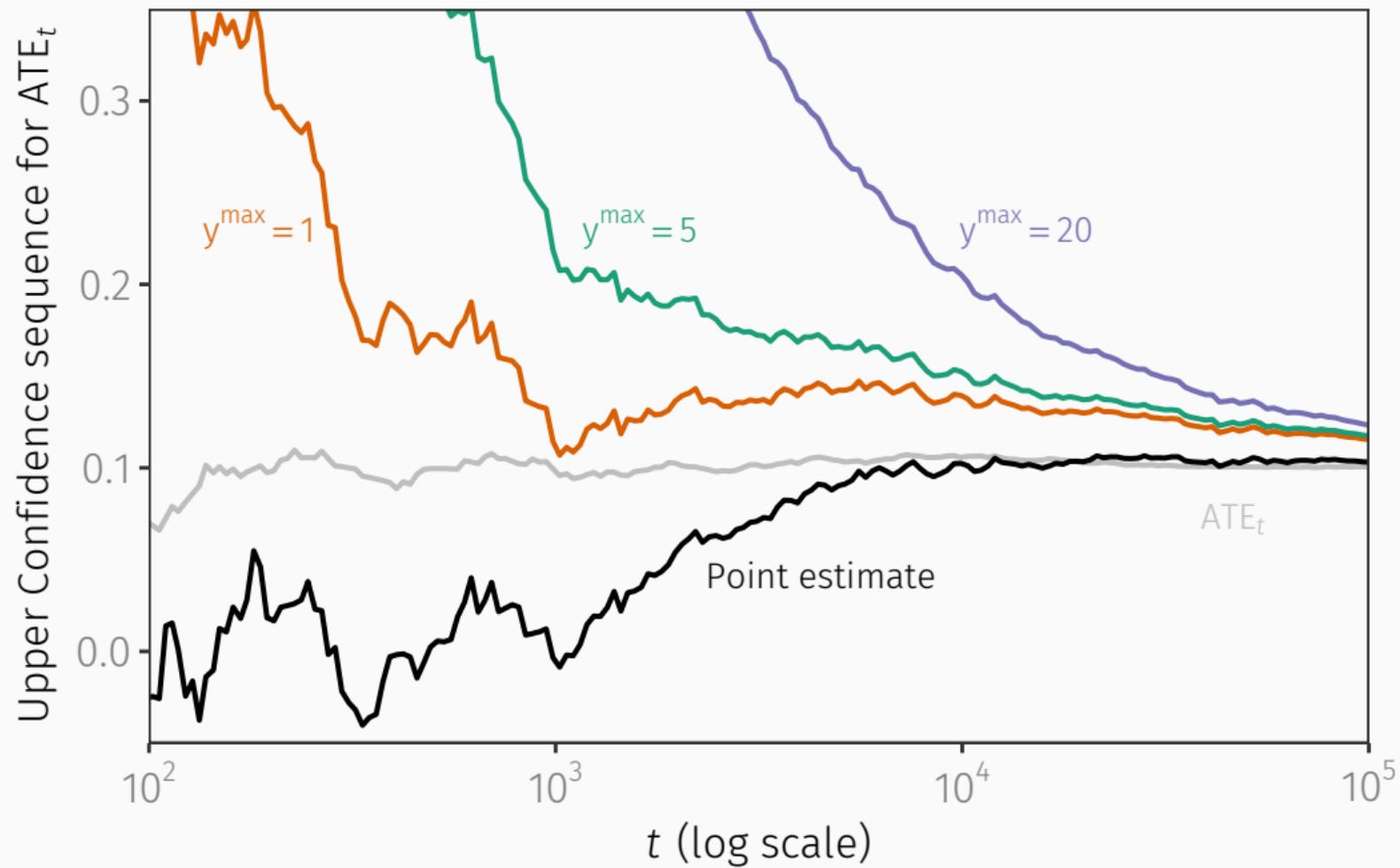
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- $u_\alpha(v) = \mathcal{O}(\sqrt{v \log v})$, so $u_\alpha(v)$ is like $z_{1-\alpha} \sqrt{v}$, but the “z-factor” grows over time (slowly).

The uniform boundary grows only slightly faster than $\mathcal{O}(\sqrt{n})$





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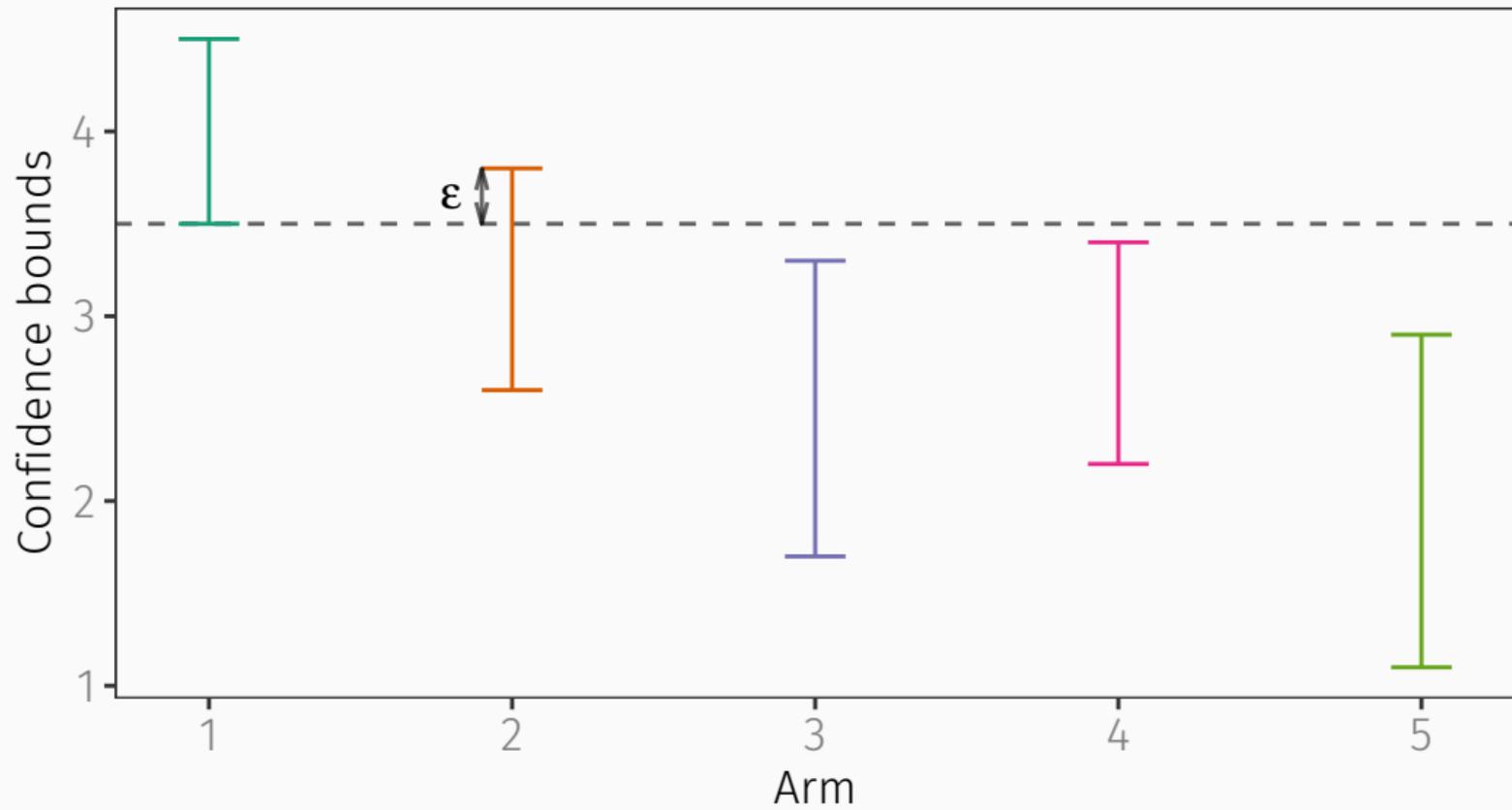
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Common strategy:

- Construct confidence sequence $(L_{kt}, U_{kt})_{t=1}^\infty$ for each arm k , so that $L_{kt} \leq \mu_k \leq U_{kt}$ for all k, t with probability at least $1 - \delta$.
- Stop the first time there exists some k_\star such that

$$L_{k_\star t} \geq U_{kt} - \epsilon \text{ for all } k \neq k_\star.$$



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Can be done in our framework, allowing more efficient stopping in nonparametric settings.

- Complete theory is work in progress

Quantile best-arm identification

Let $Q_k(p)$ denote the p^{th} quantile of arm k .

Quantile ϵ -best-arm identification with fixed confidence $1 - \delta$: choose an arm k_\star such that, with probability at least $1 - \delta$, we have $Q_{k_\star}(p + \epsilon) \geq \max_k Q_k(p)$. [Szörényi et al. 2015]

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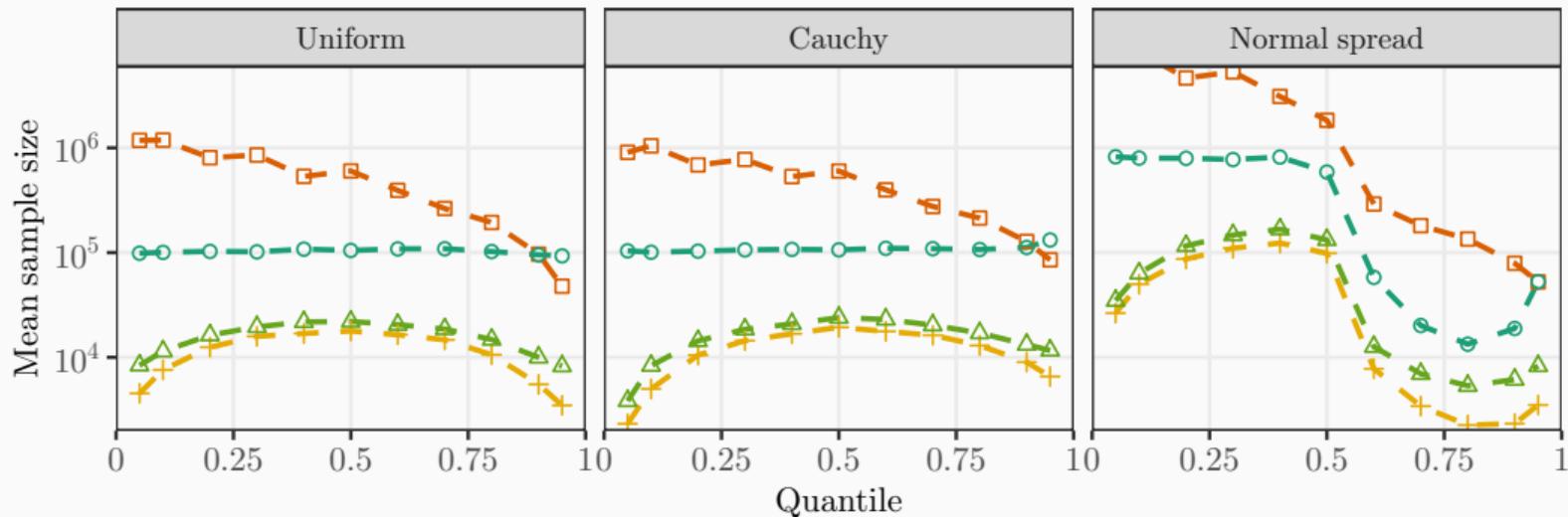
QLUCB algorithm [H. and Ramdas 2019]: at each round,

- sample arm h_t with highest LCB for $Q_k(p + \epsilon)$;
- sample arm with highest UCB for $Q_k(p)$, excluding h_t ; and
- stop when LCB for $Q_k(p + \epsilon)$ is above UCB for $Q_j(p)$ for all $j \neq k$, for some k .

[cf. Kalyanakrishnan et al. 2012]

Quantile best-arm simulations

- David and Shimkin (2016)
- △— QLUCB stitched (ours)
- Szörényi et al. (2015)
- +— QLUCB beta-binomial (ours)



A taste of the underlying framework

Reminder: sub-Gaussianity and Hoeffding bound

A random variable X is *sub-Gaussian* with variance parameter σ^2 if

$$\log \mathbb{E} e^{\lambda X} \leq \frac{\lambda^2 \sigma^2}{2} \quad \text{for all } \lambda \in \mathbb{R}. \quad (6)$$

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1. Show X_i is sub-Gaussian with variance parameter $1/4$, and
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A random variable X is *sub-Gaussian* with variance parameter σ^2 if

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Hoeffding bound (1963): if $X_i \in [0, 1]$ independent, $i = 1, \dots, t$, then

$$\mathbb{P} \left(\sum_{i=1}^t (X_i - \mathbb{E} X_i) \geq u_\psi(t\sigma^2) \right) \leq \alpha. \quad \text{Here } u_\psi(v) = \sqrt{2v \log \alpha^{-1}}, \quad \sigma^2 = \frac{1}{4} \quad (7)$$

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4. At time t , a confidence set for θ is

$$\text{Cl}_t = \left\{ \theta_0 \in \mathbb{R} : S_t^{\theta_0} < u_\alpha(V_t^{\theta_0}) \right\}.$$

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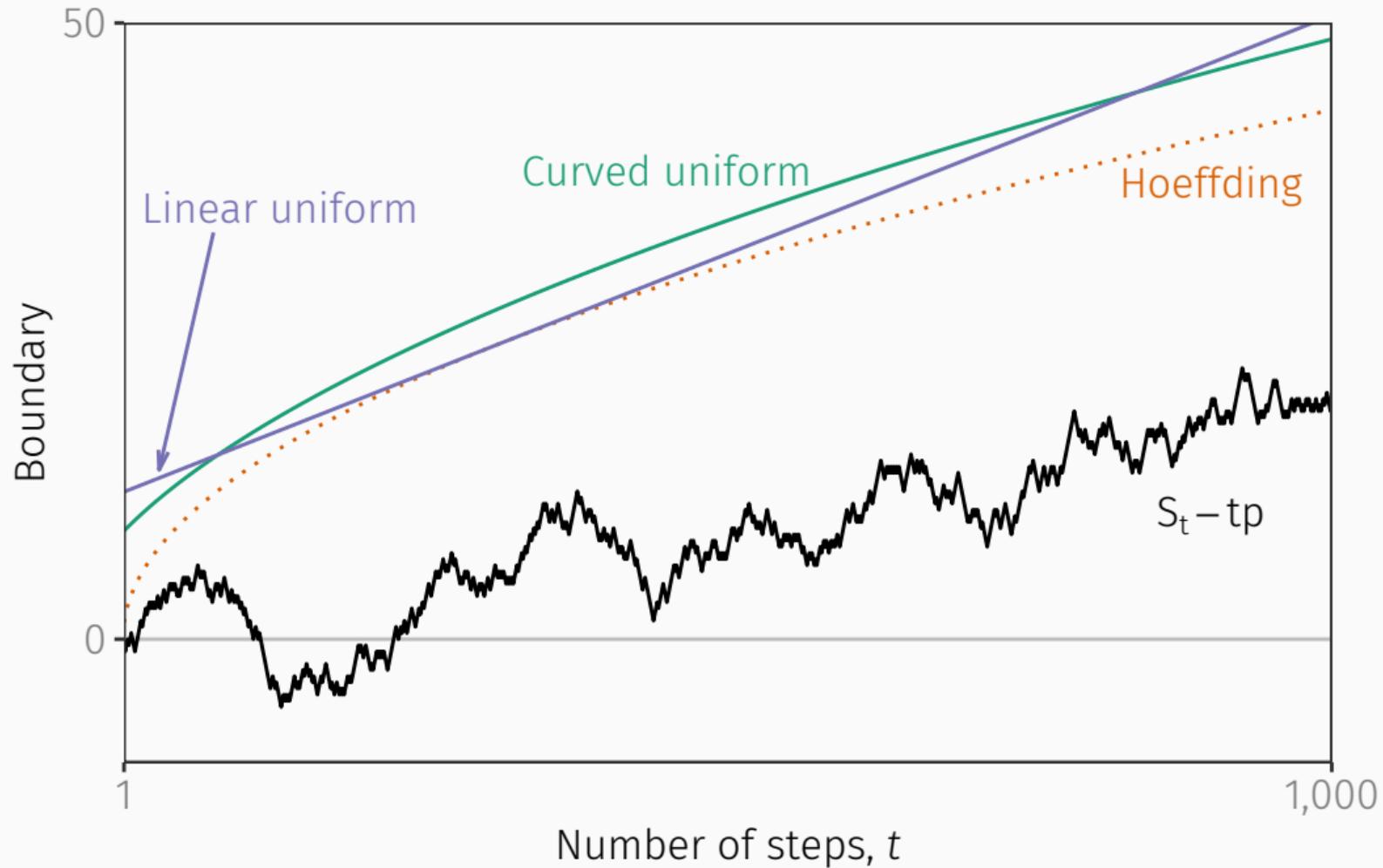
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This yields the confidence sequence

$$\left| \frac{S_t}{t} - p \right| < \frac{\log \alpha^{-1}}{\lambda t} + \frac{\lambda}{8}, \quad \text{for all } t, \text{ with probability at least } 1 - 2\alpha.$$



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